



**MICROGRID
KNOWLEDGE**
CONFERENCE SERIES

Microgrid 2019
CONFERENCE

Self-Aware Microgrid Controls

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Self-Driving Power System?



Isaac Asimov's Three Laws of Robotics (1942)

1. A robot may not injure a human being or, through inaction, allow a human being to come to harm.
2. A robot must obey the orders given it by human beings except where such orders would conflict with the First Law.
3. A robot must protect its own existence as long as such protection does not conflict with the First or Second Laws.

Isaac Asimov's Three Laws of Robotics (1942)

1. An ***autonomous power system*** may not injure a human being or, through inaction, allow a human being to come to harm.
2. An ***autonomous power system*** must obey the orders given it by human beings except where such orders would conflict with the First Law.
3. An ***autonomous power system*** must protect its own existence as long as such protection does not conflict with the First or Second Laws.

Superior Protection

Protect Assets, Environment, and People



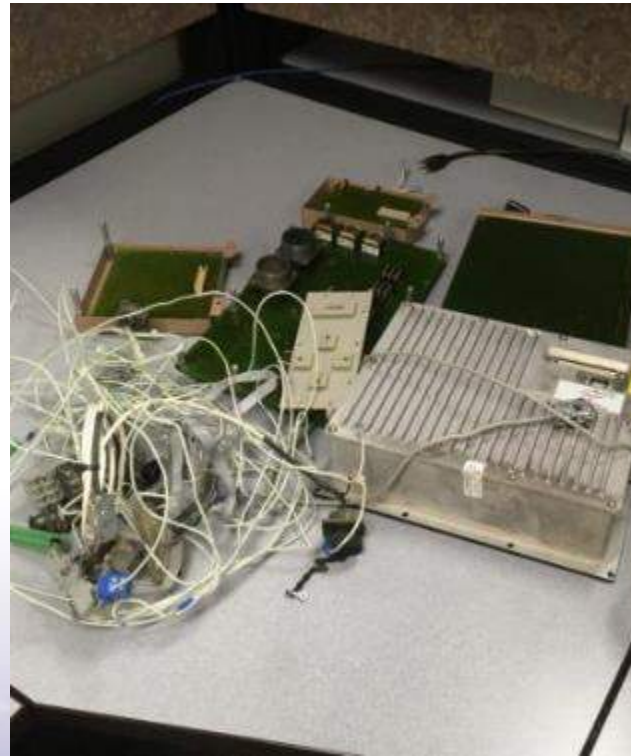
Simple and Dependable

Improving Reliability and Reducing Part Count

60 kW Diesel Genset



32 lb of Electronics

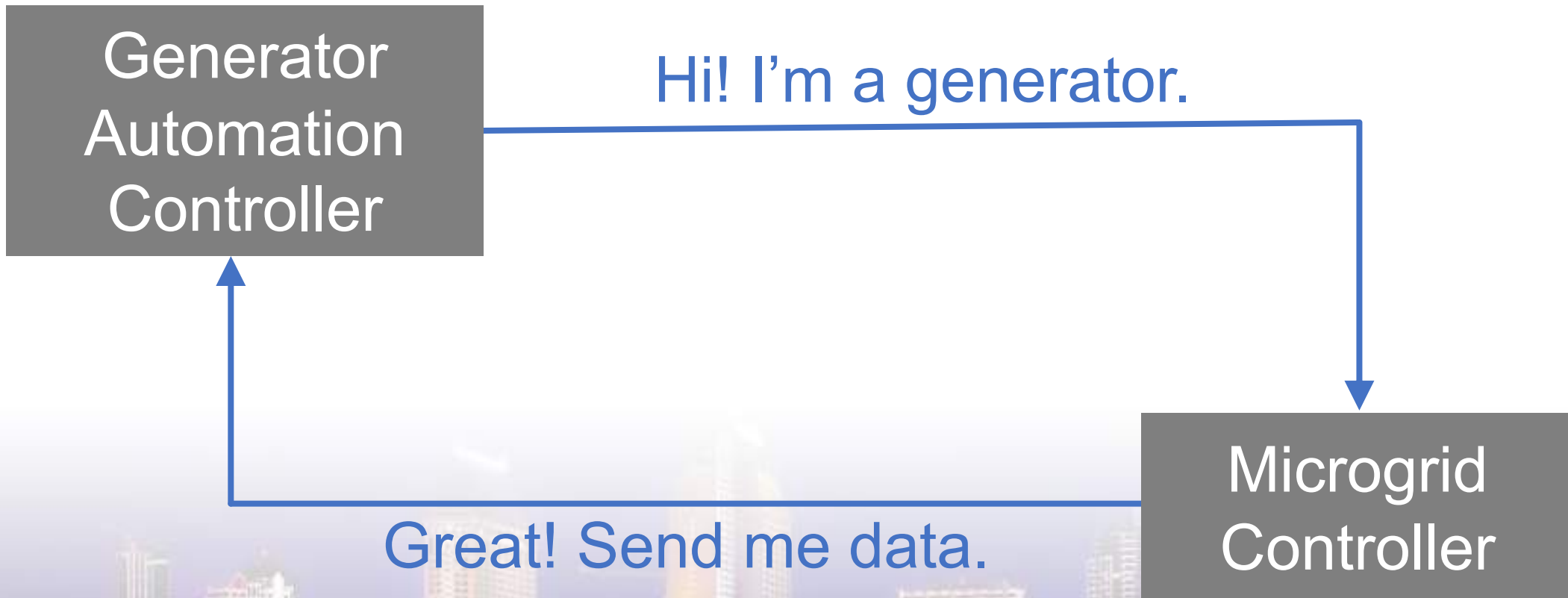


3 lb Relay Replacement



Autonomous Learning

Humans Out of the Loop



Interoperability

Making All DERs Play Nicely Together

30 kW Taylor



100 kW CAT



60 kW TQG



30 kW Gillette



↓
Loads



↓
Loads



↓
Loads

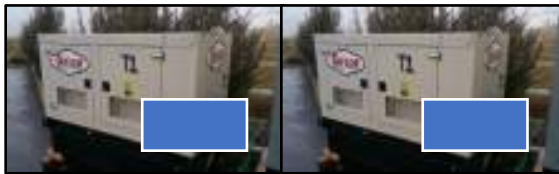


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Loads

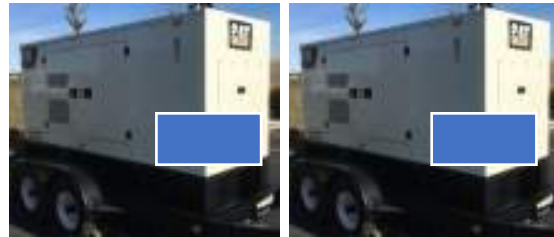
Adapts to the Mission

Same Hardware for Every DER

30 kW Taylor



100 kW CAT



60 kW TQG



30 kW Gillette



Loads



Loads



Loads



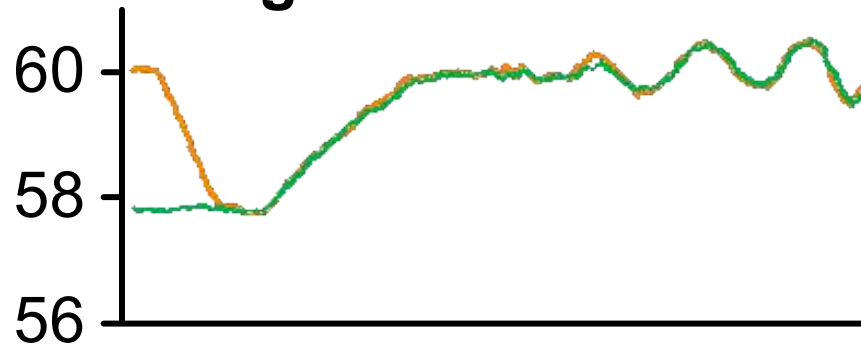
Loads

Resilience Mode

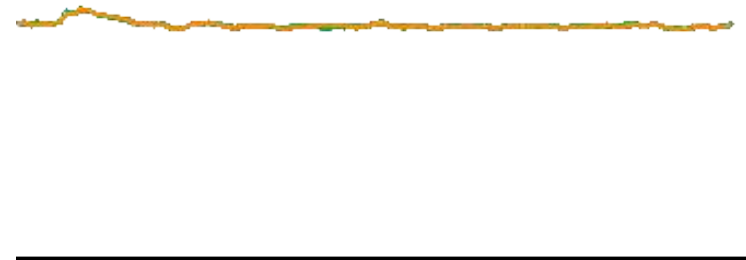
Superior Load Sharing and Frequency Control Performance

Frequency (Hz)

Engine Manufacturer



State-Space Energy Packet Controls

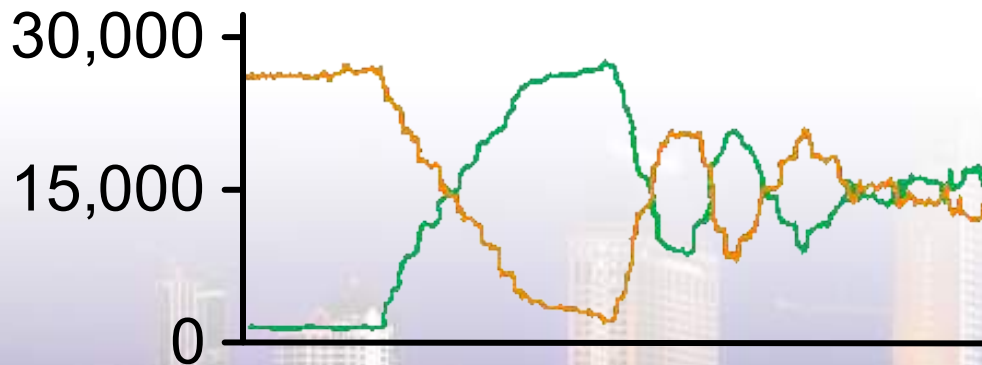


No overshoot

No integral windup

No oscillations

Power (W)

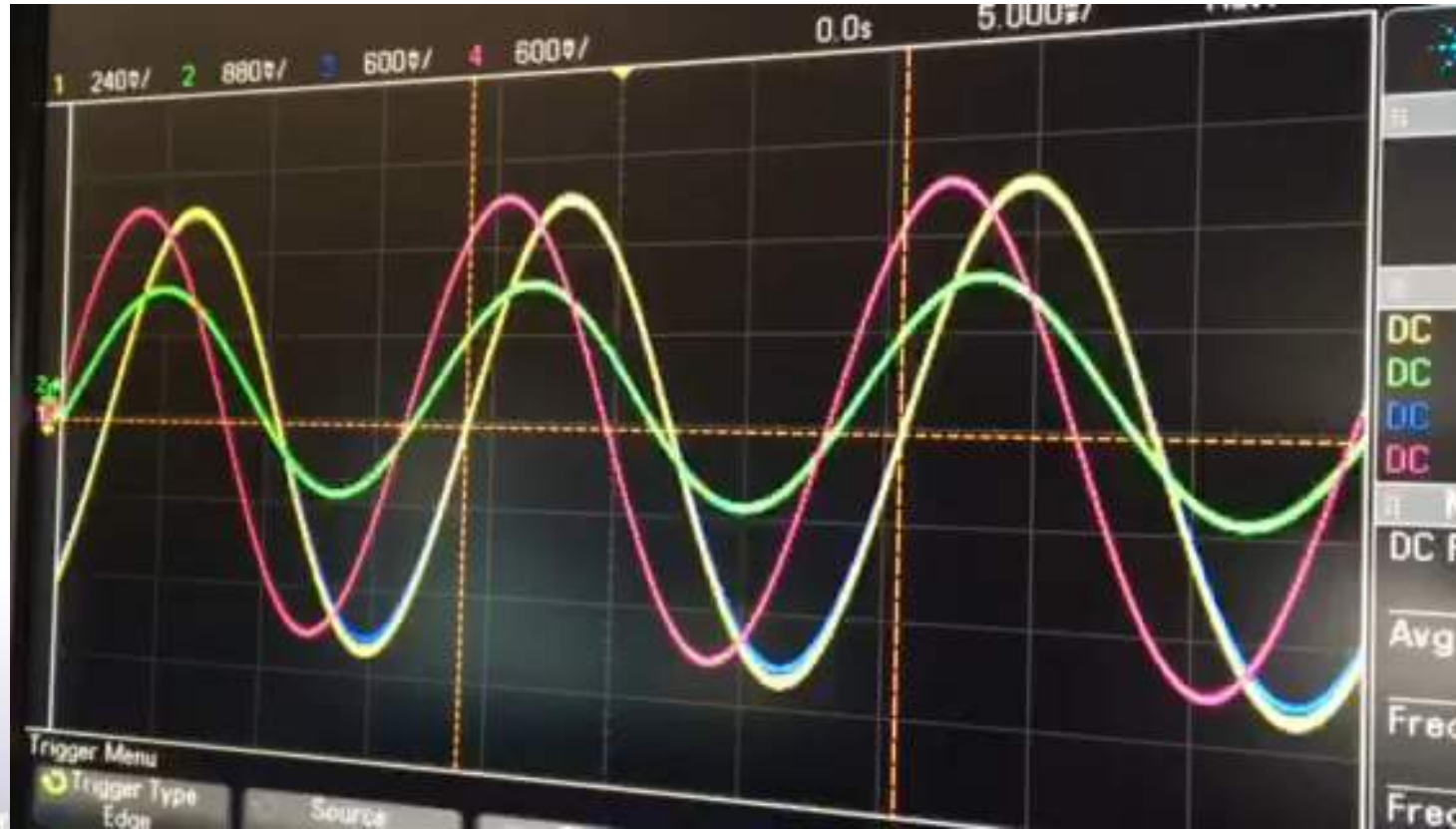


No tuning

Full interoperability

Humans Out of the Loop

Fully Autonomous Start and Synchronization

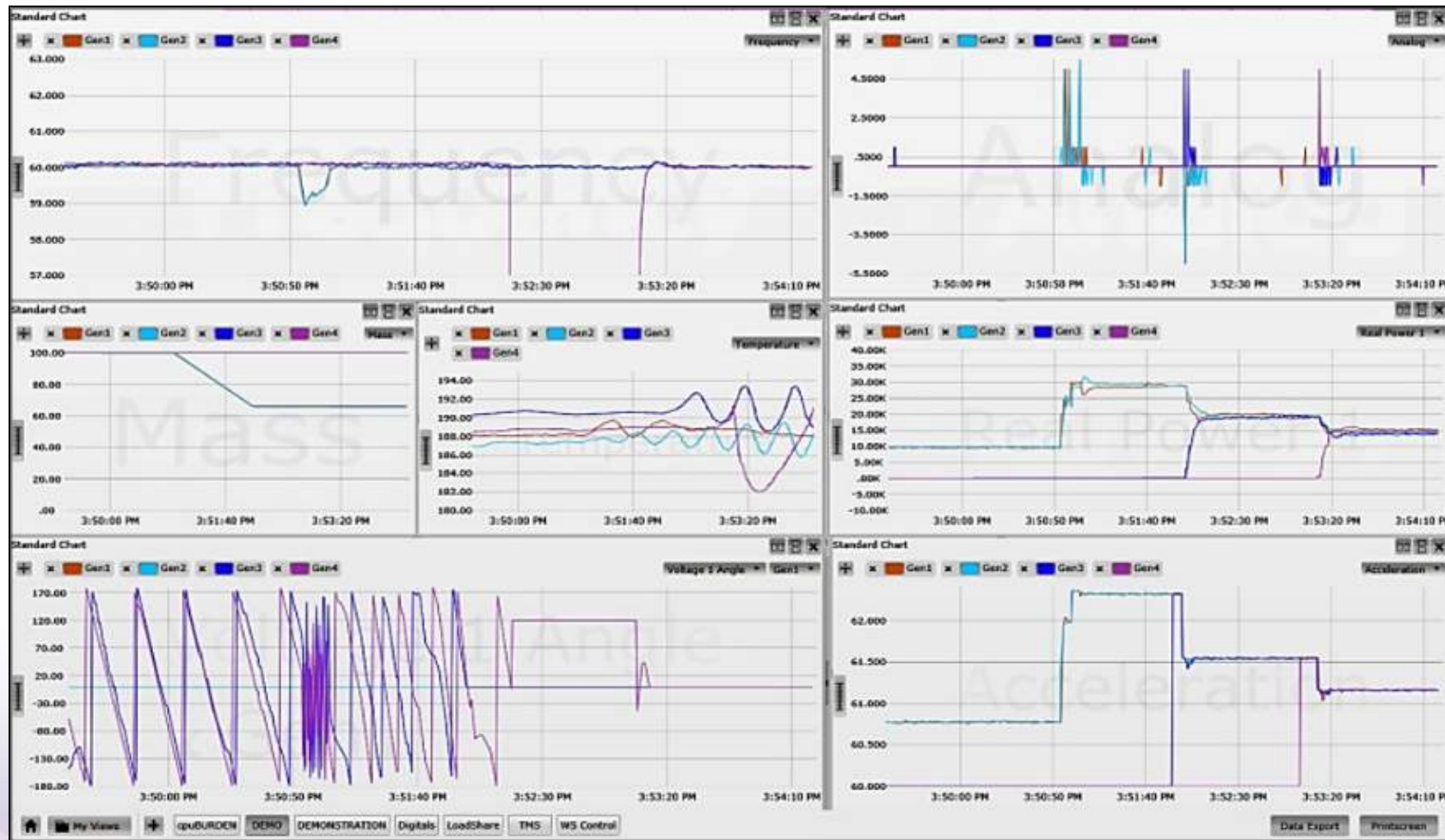


Maintenance Mode

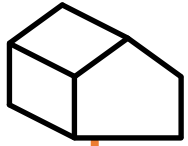
Prolong the Life of Your Engines



Time-Synchronized Condition Monitoring



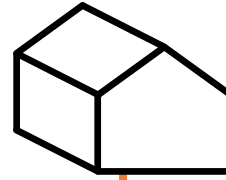
Efficiency Mode



30 kW



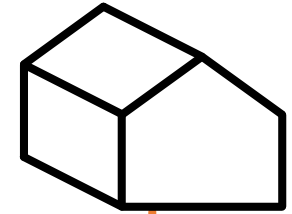
90% Efficient



60 kW



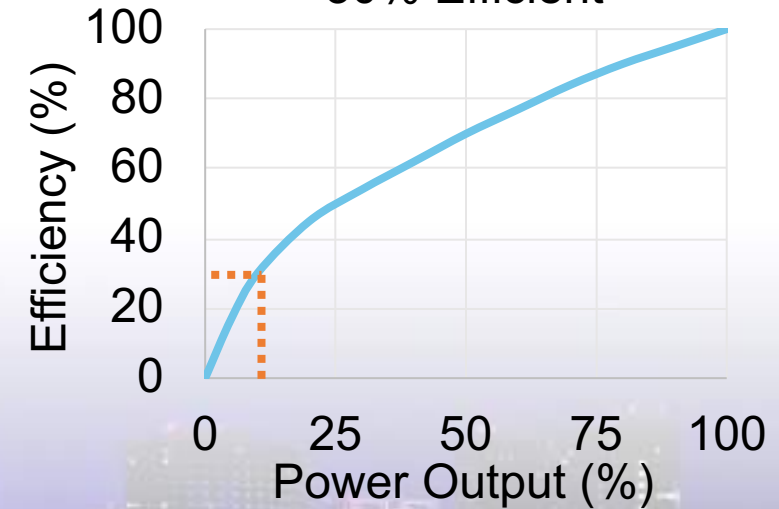
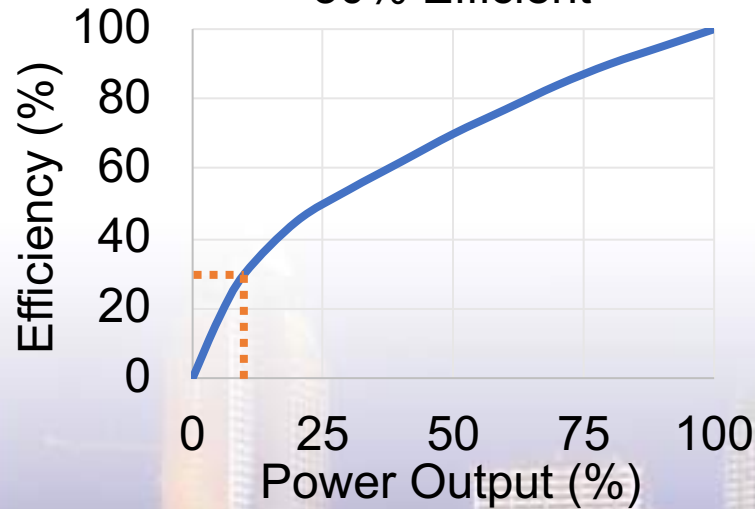
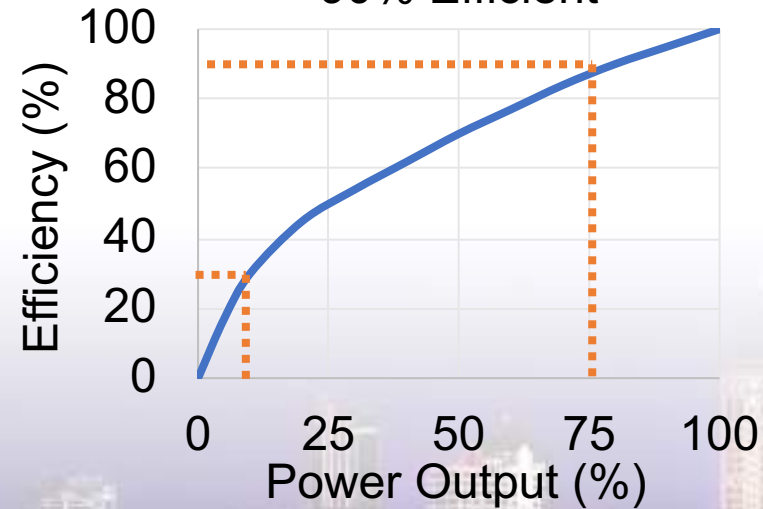
30% Efficient



100 kW

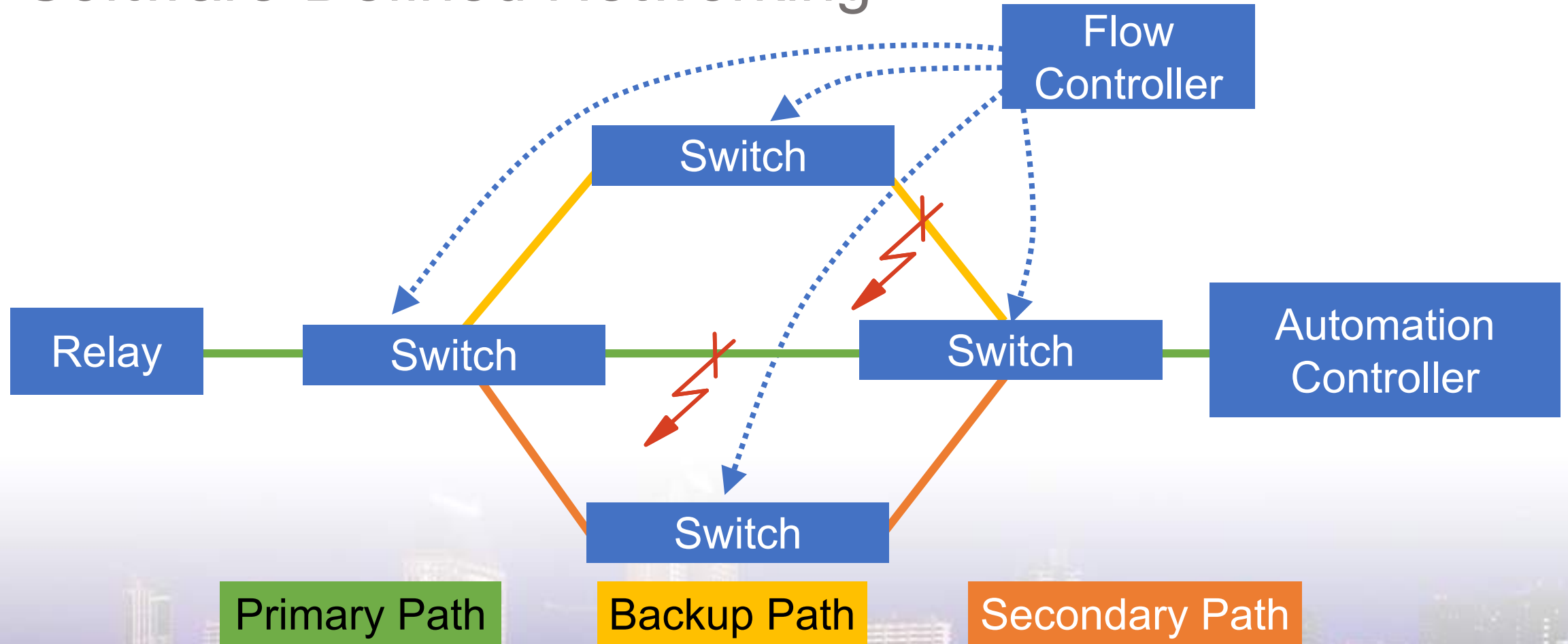


30% Efficient



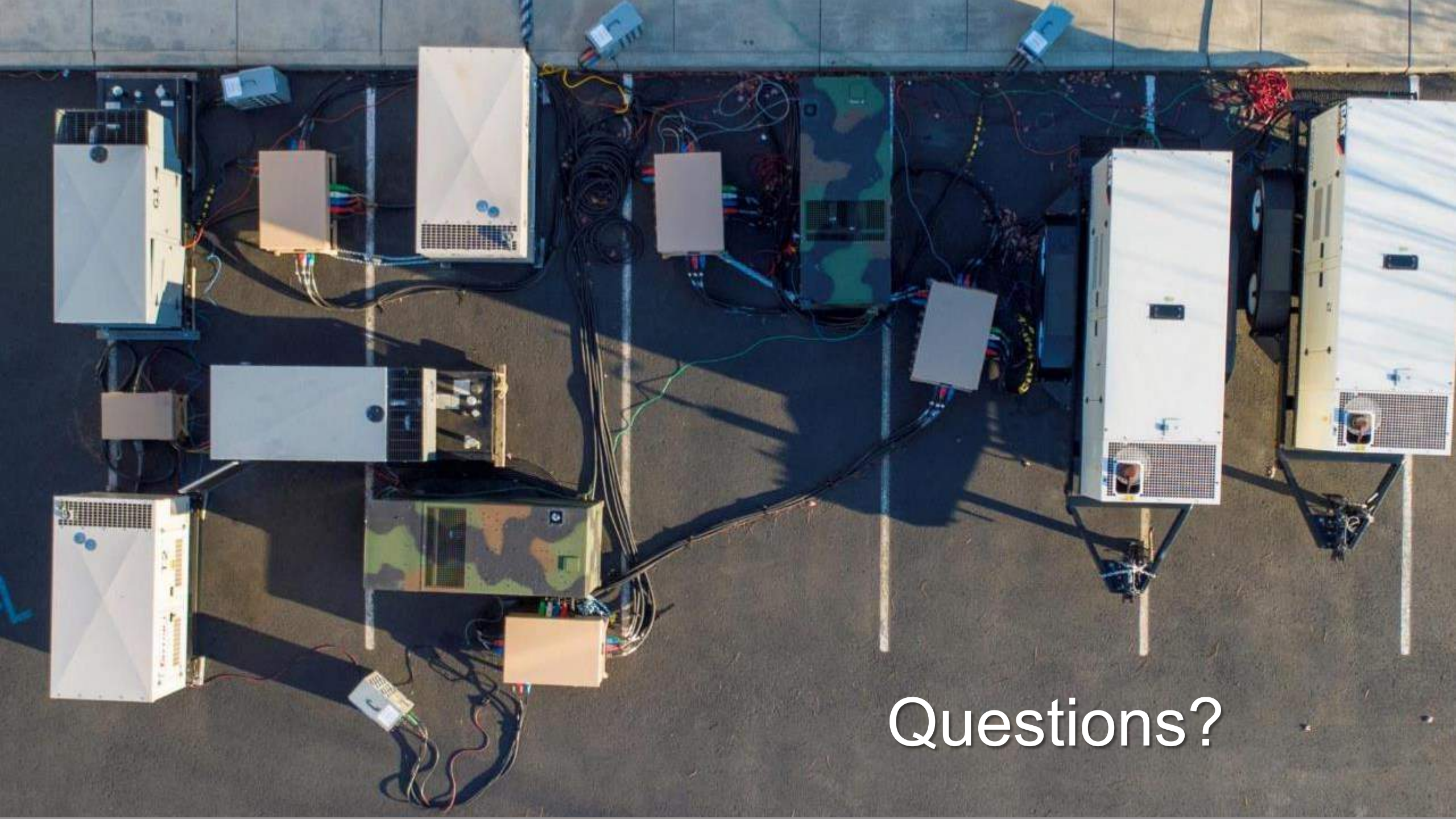
Reliable and Cybersecure Networks and Systems

Software-Defined Networking



Edmund O. Schweitzer, III, Ph.D. (1982)

- Safer—superior protection, dependability, simplicity, and cybersecurity
- More reliable—high-speed autonomous actions, interoperability, resilience mode, and humans out of the loop
- More economical—adaptability for the mission, maintenance mode, efficiency mode, and upgrades for existing systems



Questions?